

AT-WAVELENGTH METROLOGY OF X-RAY OPTICS

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AcTive X-ray & XUV OPtics

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AT-WAVELENGTH (X-RAY) METROLOGY



- **PENCIL BEAM DEFLECTOMETRY**
- **GRATING INTERFEROMETRY**
- HARTMANN SENSING
- SPECKLE-BASED METHODS





O. Hignette (ESRF)

- T. Weitkamp (now SOLEIL), C. David (SLS), I. Zanette (ESRF)
- G. Dovillaire, S. Bucourt (IMAGINE OPTIC) P. Mercere (SOLEIL), M. Idir (now NSLS-II)
- R. Cerbino (Univ. Milano)
- A. Vivo, R. Barrett (ESRF)
- I. Kozhevnikov (Institute Crystallography, Moscow)
- K. Sawhney, H. Wang (Diamond)
- J-Y. Massonnat, J. Susini (ESRF)



AT-WAVELENGTH METROLOGY

Development of X-ray sources (FEL, SR and others...) stimulate progress in optics

- minimize beam wavefront errors caused by optics
- correct incoming wavefront imperfections in view, e.g., of perfect collimation, focusing or otherwise
- diffraction-limit as ultimate goal, dimensions ~ several tens of nanometer down to 1 nm...
- At-wavelength to monitor active optics or help manufacture optics
- ☆ At-wavelength to account for specificity of interaction with matter in X-XUV optics (coherence and scattering effects with surface and/or volume), as a way to integrate factors difficult to model or that may evolve with time
 - X-ray: short wavelength > precision metrology
 - to take advantages of unique properties of X-XUV



HARD X-RAY PHASE CONTRAST IMAGING



☆ X-ray images taken at ESRF BM5 (1994)
 ☆ Human vertebra with the detector located close and far from the sample



☆ XLTP using X-ray SR beam as a wavefront reference

Ref. O. Hignette et al., SPIE Proc. vol. 3152 (1997); Review of Scientific Instruments, 76 (2005)



An X-ray slope error measuring device



 \therefore Reference wavefront: deviation from a sphere of radius 42.5 ± 0.1 m



☆ Slope standard deviation: 28 nrad (rms)

 \overleftrightarrow Wavefront standard deviation: 0.9 pm (rms) [equiv. λ / 100]

Courtesy: O. Hignette



Dynamical bending optimization of Kirkpatrick-Baez focusing optics

🙀 Combination of two perpendicular off-axis elliptical cylinder mirrors



🙀 Goal: a spherical wavefront centered on the focus (CCD location)

☆ Deviations from ideal case are read sequentially on the X-ray CCD camera as a function of the slit position

 \cancel{x} Mirror figure corrected by 2-moment bender based on flexural hinges

Interaction matrix to describe bending requires 3 wavefront measurements (unit displacement on each actuator) & linear procedure



Precision of figure metrology

Courtesy: O. Hignette

on positioning: 20 nm on shap

on shape: 0.25 nm on 100 mm mirror

Precision consistent with diffraction-limited operation



EXAFS MEASUREMENTS USING WIDE-BAND MULTILAYER KB OPTICS

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GRATING INTERFEROMETRY







Au grating (2 μ m pitch)

 \Rightarrow presence of object distorts wavefront > deflects the beam

> local displacement of the fringes > different intensity at the detector

intensity correlated to first derivative of wavefront phase > differential
phase contrast

phase-stepping interferometry allows to separate absorption from phase: phase gradient image and transmission signal

Ref. T. Weitkamp et al. Optics Express, 13 (2005)

GRATING INTERFEROMETRY European Sy

 \cancel{x} Phase stepping interferometry: linear transverse scan of one of the



Phase stepping interferometry: measure of BM5 beam wavefront



g2: pitch 2nd grating; d: inter-grating distance; ϕ : fringe phase in the image

Phase gradient in x-direction:
$$\frac{\partial \Phi(x,y)}{\partial x} = \frac{g_2}{\lambda d} \varphi(x,y)$$
 > Radius_v: 37.203 m



GRATING INTERFEROMETRY



 \overleftrightarrow Scattering signal and phase derivative in x and y directions

 \Rightarrow Helps overcoming limitations due to presence of a blind direction



Ref. I. Zanette, T. Weitkamp, T. Donath, S. Rutishauser, C. David, PRL, 105 (2010)



2D-GRATING INTERFEROMETER



Ref. I. Zanette, T. Weitkamp, T. Donath, S. Rutishauser, C. David, PRL, 105 (2010)



Wavefront sensing and adaptive optics in X-ray range

Schack-Hartmann wavefront sensor from Imagine Optic (HASO)

Automatic KB alignment already achieved using soft X-rays (3 keV) Ref. P. Mercère, M. Idir, T. Moreno, G. Cauchon, G. Dovillaire, X. Levecq, L. Couvet, S. Bucourt, P. Zeitoun, Optics Letters, 31, 2 (2006).

 \Rightarrow Hartmann grid for hard X-rays (E= 14 keV)



Multilayer-coated mirror, 170 mm, 8.1 mrad at 14 keV, trapezoidal shape





access to wavefront local slopes (derivative) by sampling the incoming beam through a Hartmann grid

 \Rightarrow each sub-aperture providing its own spot on a CCD camera, the sensor delivers a set of {x,y} spot centroid positions or Hartmann pattern

Vslit= 1.15 mmL_{mirror}= 142 mmD= 0.10 mexpo time: 1.3 s



wavefront obtained by integration of the local slope, quality depending on the number of sub-apertures (higher is better but must avoid overlapping)



HARTMANN SENSING

Vslit= 1.15 mm





Residual wavefront allows to calculate intensity profile at the focus

Before correction: 2.0 nm rms, 6.8 nm PV



After correction: 1.4 nm rms, 5.0 nm PV



The European Light Source



results on reflected wavefront expected to be better by liberating constraint on the tilt

 \Rightarrow overnight monitoring of the wavefront sagittal radius of curvature:



Fluctuation ~ 0.1 mm corresponding to wavefront change ~ 0.3 nm



X-ray speckle: random intensity pattern created by irradiation of a scattering object with a partially coherent light

☆ Near-field regime: speckle grains do not change in size and shape over a distance $z_{NF} \sim dD^2 / \lambda$ *d: speckle grain size D: transverse coherence*

Ref. R. Cerbino, L. Peverini, M. Potenza, A. Robert, P. Bösecke, M. Giglio, Nature Physics 4 (2008)

Generation of a static speckle pattern: solid membrane containing phase objects (e.g., cellulose)

ESRF BM5 beamline: speckle pattern behind scattering membrane located downstream crystal monochromator beam and Be windows





Tracking the speckle pattern using digital image correlation



Subset tracking between images with 0.01 pixel accuracy

Absolute configuration



Measurement of the wavefront state at several detector planes



Deviation from ellipsoid (in nm) E: 17 keV, two images distant 500 mm



- Wavefront radius: $R_V = 37.43$ m, $R_H = 40.37$ m with picometer precision
- Spatial resolution: 5.8 μ m over 4 mm x 4.6 mm
- Precision on slope: better than 0.1 μrad

2D reconstruction of the mirror surface by inverse ray-tracing process



PhD thesis of Sebastien Berujon



CONCLUSION

\Rightarrow At wavelength metrology:

- easier if end user/application based at large research facility source
- shearing interferometry used at laboratory source (*Röntgen award 2010*)
- speckle tracking: simplicity of the instrumentation (work in progress)

 \Rightarrow In-situ at-wavelength metrology to enable accurate measurements on:

- beamline optical elements
- mirror figure correction (active optics or mirror surface figuring)
- out-of-focus metrology desired (user experiments and routine performance control, on line mirror figuring,)
 - mirror figuring: surface profile needed

\Rightarrow Precision on slope error can reach 0.1 to 0.03 μ rad

Limits of some at-wavelength methods

CONCLUSION

- sampling limits with short mirrors or viewed at small angle
- (e.g., hard x-rays on uncoated mirror surface)
 - 2D observation vs one direction at a time
 - shearing interferometry: strongly curved surfaces
- XST: minimum curvature to benefit from beam magnification and gain sensitivity

Complementarity with other techniques (calibration, limited access to X-XUV...)

• access to NOM, LTP, stitching interferometry... is important