## Calibration of a Hall Probe Array IMMW 20

6th June 2017 | Jan Henry Hetzel | Institut für Kernphysik 4, FZ-Jülich<br>Presentation for HEDI - Measurement of the HESR Dipoles: U. Bechstedt, J. Böker, C.<br>Ehrlich, I. Engin, J. Hetzel, S. Quilitzsch, H. Soltner, P. Tripathi

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## The "Rotating Hall Probes" Device



- Purpose: measurement of multipole components
- Array of 8 3D-Hall probes
- Rotatable by Piezo-Motor
- Diameter of Disc 80 mm
- Technical details: (Talk to us, we're here)
- Problem: Conventional calibration methods not possible (dimension of device!)


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## The "Rotating Hall Probes" Device



This talk: Just give an idea of used calibration method. So just probes in radial direction, up to first order.

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## Objective of Calibration Campaign

## Estimate relevant quantities




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View from TOP


Inner Quantities

$$
(i=0, . ., N-1)
$$

- Roll angle $\alpha_{i}$


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- Roll angle $\alpha_{i}$
- Pitch angle $\beta_{i}$


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- Yaw angle $\gamma_{i}$
- proportionality


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- Roll angle $\alpha_{i}$
- Pitch angle $\beta_{i}$
- Yaw angle $\gamma_{i}$
- angular position $\varphi_{i}$
- radial position
$R+r_{i}$
- proportionality


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( $i=0, . ., N-1$ )
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Outer Quantities

- Roll angle A
- Pitch angle B


## Objective of Calibration Campaign

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View from TOP


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- Pitch angle $\beta_{i}$
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Outer Quantities

- Roll angle $A$
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## Principle



Estimate angles from Harmonic measurements in "conventional" resistive dipoles and quadrupoles.

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Estimate angles from Harmonic measurements in "conventional" resistive dipoles and quadrupoles.

## Measurement

## Example of one measurement in the dipole


all 8 probes, $r$-direction, 512 angular positions
$\Rightarrow$ needed for analysis: model of measurement

## Model

Measured value $U^{\prime}(\vec{x})$ :

$$
U^{\prime}(\vec{x})=\frac{\vec{B}(\vec{x})}{u} \cdot \vec{n}_{\text {probe }}(\vec{x})+U_{0}
$$

proportionality factor: $u$
zero gauss offset: $U_{0}$
probe orientation: $\vec{n}_{\text {probe }}$
$B$ field at probe position $\vec{x}: \vec{B}(\vec{x})$

Model

$$
U_{i}\left(\vec{x}_{i}\right):=\left(U_{i}^{\prime}-U_{0, i}\right)=\frac{1}{u_{i}} B\left(\vec{x}_{i}\right) \cdot \vec{n}_{i}
$$

Orientation of probe i:

$$
\begin{aligned}
& \vec{n}_{i}=\mathbf{M}_{\mathrm{yaw}, \Gamma} \cdot \mathbf{M}_{\mathrm{pitch}, B} \cdot \mathbf{M}_{\mathrm{roll}, A} \cdot \mathbf{M}\left(\phi+i \cdot \frac{\pi}{4}\right) \cdot \mathbf{M}_{\varphi, i} \cdot \mathbf{M}_{\mathrm{y} \cdot, \gamma, i} \cdot \mathbf{M}_{\mathrm{p} \cdot, \beta, i} \cdot \mathbf{M}_{\mathrm{r}, \alpha, i} \cdot \overrightarrow{\boldsymbol{e}} \\
& \vec{e}=(1,0,0)^{T}
\end{aligned}
$$

## Model

Order of multiplication defines interpretation of angles.

$$
\vec{n}_{i}=\mathbf{M}_{\mathrm{yaw}, \Gamma} \cdot \mathbf{M}_{\mathrm{pitch}, B} \cdot \mathbf{M}_{\mathrm{roll}, A} \cdot \mathbf{M}\left(\phi+i \cdot \frac{\pi}{4}\right) \cdot \mathbf{M}_{\varphi, i} \cdot \mathbf{M}_{\mathrm{y} \cdot, \gamma, i} \cdot \mathbf{M}_{\mathrm{p} ., \beta, i} \cdot \mathbf{M}_{\mathrm{r} ., \alpha, i} \cdot \overrightarrow{\boldsymbol{e}}
$$

Order is chosen such that

$$
\mathbf{M}_{\mathrm{roll}, A} \cdot \mathbf{M}\left(\phi+i \cdot \frac{\pi}{4}\right) \cdot \mathbf{M}_{\varphi, i}
$$

can be combined to one rotation with angle $\phi+A+\varphi_{i}+i \cdot \frac{\pi}{4}$.

## Model

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can be combined to one rotation with angle $\phi+\boldsymbol{A}+\varphi_{i}+i \cdot \frac{\pi}{4}$.
Further simplification: Shift angle of measurements by $-i \cdot \frac{\pi}{4}$

## Model

Order of multiplication defines interpretation of angles.
$\vec{n}_{i}=\mathbf{M}_{\mathrm{yaw}, \Gamma} \cdot \mathbf{M}_{\mathrm{pitch}, B} \cdot \mathbf{M}_{\mathrm{roll}, \boldsymbol{A}} \cdot \mathbf{M}(\phi) \cdot \mathbf{M}_{\varphi, i} \cdot \mathbf{M}_{\mathrm{y} \cdot, \gamma, i} \cdot \mathbf{M}_{\mathrm{p}, \beta, i} \cdot \mathbf{M}_{\mathrm{r} ., \alpha, i} \cdot \overrightarrow{\boldsymbol{e}}$
Order is chosen such that

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\mathbf{M}_{\mathrm{roll}, \boldsymbol{A}} \cdot \mathbf{M}(\phi) \cdot \mathbf{M}_{\varphi, i}
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can be combined to one rotation with angle $\phi+A+\varphi_{i}$.

Further simplification: Shift angle of measurements by $-i \cdot \frac{\pi}{4}$

## Measurement

## Example of one measurement in the dipole



## Measurement

## Example of one measurement in the dipole



## Model

$$
U_{i}(\phi)=\frac{1}{u_{i}} \vec{B}\left(\vec{x}_{i}(\phi)\right) \cdot \vec{n}_{i}(\phi)
$$

description of $\vec{B}$ :
perfect dipole: $\vec{B}_{1}=(0, B, 0)^{\mathrm{T}}$
perfect quadrupole: $\vec{B}_{2}=g \cdot\left(\begin{array}{lll}0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0\end{array}\right) \cdot \vec{x}(\phi)$
perfect sextupole: $\vec{B}_{3}=m \cdot\left(2 x_{1}(\phi), x_{1}^{2}(\phi)+x_{2}^{2}(\phi), 0\right)^{\mathrm{T}}$
more realistic dipole: $\vec{B}=\vec{B}_{1}+\vec{B}_{3}$

## Model

$$
U_{i}(\phi)=\frac{1}{u_{i}} \vec{B}\left(\vec{x}_{i}(\phi)\right) \cdot \vec{n}_{i}(\phi)
$$

Position of probe i:

$$
\vec{x}_{i}(\phi)=\mathbf{M}_{\mathrm{yaw}, \Gamma} \cdot \mathbf{M}_{\mathrm{pitcch}, B} \cdot \mathbf{M}\left(A+\phi+\varphi_{i}\right) \cdot\left(\begin{array}{c}
R+r_{i} \\
0 \\
0
\end{array}\right)+\left(\begin{array}{c}
x_{0} \\
y_{0} \\
z_{0}
\end{array}\right)
$$

## Model

$$
U_{i}(\phi)=\frac{1}{u_{i}} \vec{B}\left(\vec{x}_{i}(\phi)\right) \cdot \vec{n}_{i}(\phi)
$$

This is now to be expressed in Fourier coefficients:

$$
U_{i}(\phi)=a_{0}+\sum_{k=1}^{\infty} a_{k} \cos (k \phi)+b_{k} \sin (k \phi)
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## Model

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$$

Simplifying assumption: all imperfections are of same order of magnitude $\xi$
$\rightarrow$ use Taylor expansion up to order $\mathcal{O}\left(\xi^{n}\right)$

## Fourier Coefficients

Radial probes, first order $\mathcal{O}(\xi)$
(perfect) Dipole:

$$
\begin{aligned}
& a_{0, D, i}=0 \\
& a_{1, D, i}=\left(A+\varphi_{i}+\alpha_{i}\right) \cdot \frac{B}{u_{i}} \\
& b_{1, D, i}=1 \cdot \frac{B}{u_{i}}
\end{aligned}
$$

Quadrupole:

$$
a_{0, Q, i}=0
$$

$$
\begin{aligned}
& a_{1, Q, i}=\frac{g}{u_{i}}\left(y_{0}+\left(A^{\prime}+\varphi_{i}+\alpha_{i}\right) \cdot x_{0}\right) \\
& b_{1, Q, i}=\frac{g}{u_{i}}\left(-\left(A^{\prime}+\varphi_{i}+\alpha_{i}\right) \cdot y_{0}+x_{0}\right) \\
& a_{2, Q, i}=\frac{g}{u_{i}}\left(R+r_{i}\right) \cdot\left(2 A^{\prime}+2 \varphi_{i}+\alpha_{i}\right) \\
& b_{2, Q, i}=\frac{g}{u_{i}}\left(R+r_{i}\right)
\end{aligned}
$$

## remaining task

Combine measured Fourier coefficients to estimate angles.

## Caveat

## Mismatch of "outer" roll angle A




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## Mismatch of "outer" roll angle A



## Solution

## Use field to find orientation

## Fourier coefficients

Dipole:
$a_{1, D, i}=\left(A+\varphi_{i}+\alpha_{i}\right) \cdot \frac{B}{u_{i}}$
Quadrupole:
$a_{1, Q, i}=\frac{g}{u_{i}}\left(y_{0}+\left(A^{\prime}+\varphi_{i}+\alpha_{i}\right) \cdot x_{0}\right)$
Reminder: Rotation around longitudinal axis $\propto A+\varphi_{i}+\phi$ $\Rightarrow$ Mismatch of A can be "absorbed" in initial $\phi$

Shift angle of measurements, such that in Dipole:

$$
a_{1, D, 0}=0
$$

## Problem solved I

Mismatch of "outer" roll angle A in dipole


## Solution

## Use field to find orientation

## Fourier coefficients

Dipole:
$a_{1, D, i}=\left(\boldsymbol{A}+\varphi_{i}+\alpha_{i}\right) \cdot \frac{B}{u_{i}}$
Quadrupole:

$$
a_{1, Q, i}=\frac{g}{u_{i}}\left(y_{0}+\left(A^{\prime}+\varphi_{i}+\alpha_{i}\right) \cdot x_{0}\right)
$$

Wanted: $A=A^{\prime}$
already aligned: $a_{1, D, 0}=0$ Consequently: $a_{1, Q, 0} \stackrel{!}{=} \frac{g}{u_{i}} y_{0}$ or

$$
a_{1, Q, 0}\left(x_{0}\right)=\text { const. }
$$

## Multiple Measurements at Different Horizontal Positions


choose initial $\phi$ such, that
$a_{1, Q, 0}=$ const.
Boundary condition:

$$
\frac{a_{2, Q, 0}}{b_{2, Q, 0}}=2 A^{\prime}+\alpha_{0}
$$

same for all measurements.

## Multiple Measurements at Different Horizontal Positions

## Example





Desired initial $\phi$ can be found by

$$
\phi=-\frac{\frac{\partial a_{1, Q, 0}}{\partial x_{0}}\left(x_{0}\right)}{\frac{\partial b_{1, Q, 0}}{\partial x_{0}}\left(x_{0}\right)}=-\left(A^{\prime}+\alpha_{0}\right)
$$

## Problem Solved II?

Mismatch of "outer" roll angle A in dipole and quadrupole



## Problem Solved II?

## Main source of systematic errors

- displacement has to be carefully matched to horizontal axis
- rely on just a few measurements
- higher order multipoles especially in the outer regions present


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## I Want You!

Better ideas of how to align measurements in dipole and quadrupole welcome.

## Combination of Measured Coefficients

## Radial probes $\mathcal{O}(\xi)$

$$
\begin{gathered}
\alpha_{i}=2 \frac{a_{1, D, i}}{b_{1, D i}}-\frac{a_{2, Q, i}}{b_{2, Q, i}} \\
\phi_{i}=\frac{a_{2, Q, i}}{b_{2, Q, i}}-\frac{a_{1, D, i}}{b_{1, D, i}}+\alpha_{0} \\
R+r_{i}=\frac{b_{2, Q, i}}{\frac{\partial b_{1, Q, i}}{\partial x_{0}}\left(x_{0}\right)}
\end{gathered}
$$

Knowledge of proportionality factors $u_{i}$ not needed at this stage.
Redundancy between $A$ and one out of $3 \times 8 \varphi_{i} \Rightarrow$ set $\varphi_{0}=0$ for radial probe.

## Results

## Radial probes




## Systematic Uncertainties

- During measurement: "Flip and repeat"
- $\xi_{\text {max }} \approx 0.02 \mathrm{rad} \Rightarrow \mathcal{O}\left(\xi^{2}\right) \approx 5 \cdot 10^{-4} \mathrm{rad}$
- sextupole contribution, $\mathcal{O}(\xi)$ ):

$$
\begin{gathered}
a_{1} \cdot u=m \cdot\left(2 x y+(A+\varphi+\alpha)\left(x^{2}+y^{2}\right)+(R+r)^{2} A\right) \\
b_{3} \cdot u=m \cdot(R+r)^{2}
\end{gathered}
$$

even for maximum measured $b_{3}$ correction to $a_{1}=\mathcal{O}\left(x^{2}\right)$

## Conclusion \& Outlook

- successfully determined positions and roll angles of angular probes to first order
- determine proportionality factors $u_{i}$ by comparison with NMR measurements
- determine remaining angles by using second order
- determine remaining angles by additional measurements in solenoid


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