



... riding the wave

Development of new measurement capabilities at Kyma

06/06/2017

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Presentation of Kyma

- ◆ **Kyma Srl was formally established on August 28th 2007**
 - ◆ *Specific purpose was to realize the undulators for the FERMI@Elettra Project*
- ◆ **All the 18 undulators delivered by June 2011**
- ◆ **“External” market entered in 2010**
- ◆ **By current date Kyma made more than 50 undulators and 60 phase shifters**
 - ◆ *Most of the undulators are EPUs*
 - ◆ *Some unique projects for INFN, Cornell*

Kyma is an industrial company specialized in insertion devices



Developments in magnetic measurements

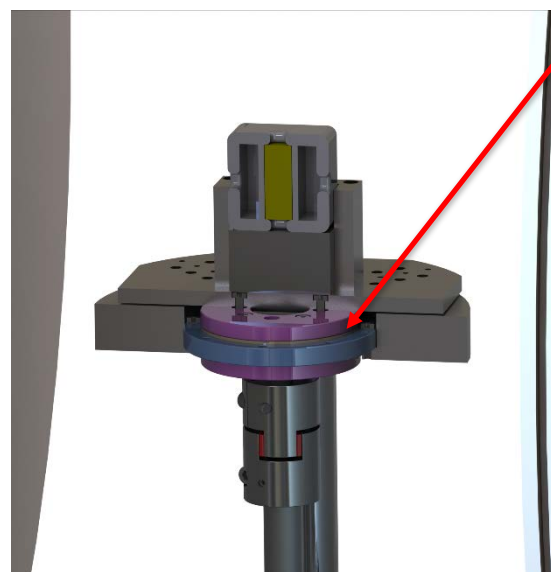
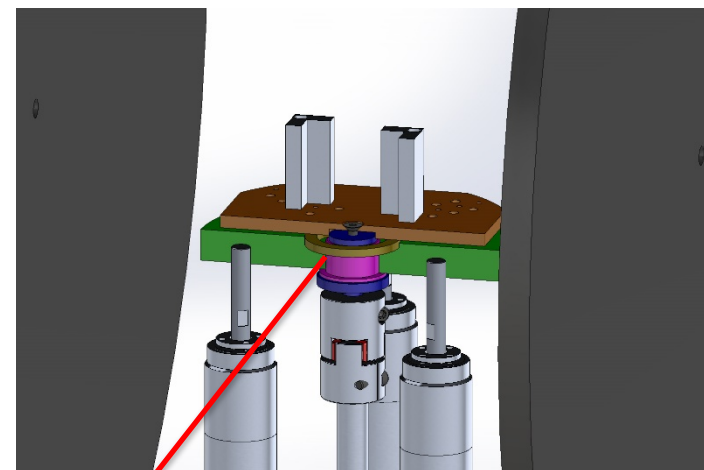
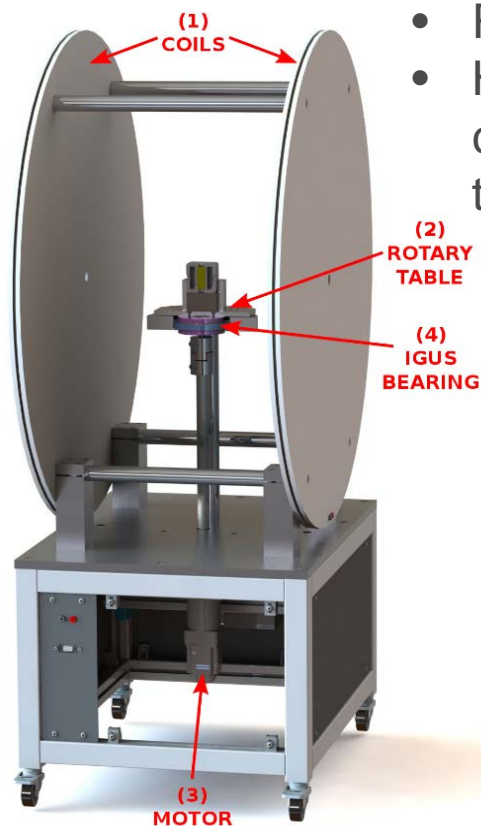
- ◆ **Helmholtz coil improvement**
- ◆ **Measurement bench for CCU**
- ◆ **New 3D hall probe from Senis – Type C**
- ◆ **Universal bench CS**
- ◆ **Pulsed wire from CSU**

Improved Helmholtz coil

Helmholtz coil for industrial quantities

Old system

- PTFE friction bearing
- Radial only
- Requires maintenance
- Heated when used continuously for long time

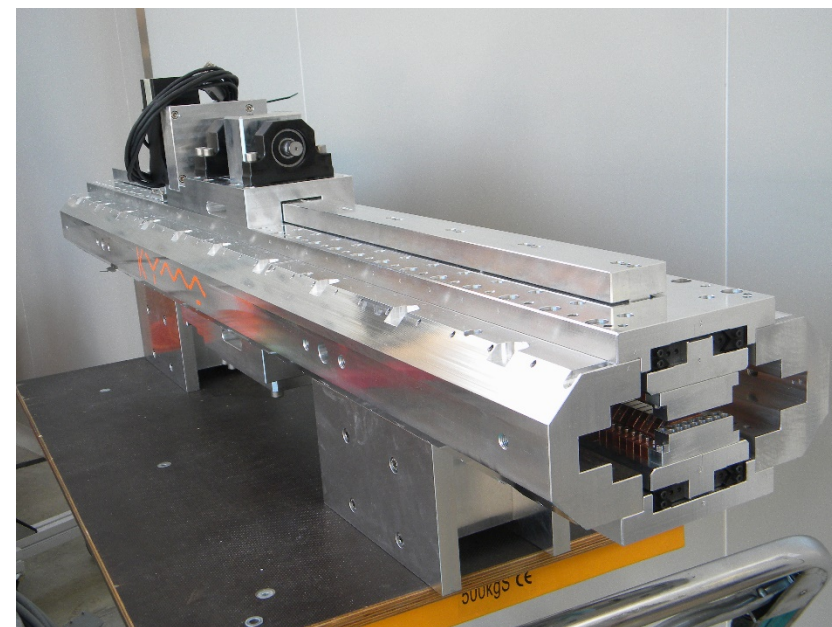
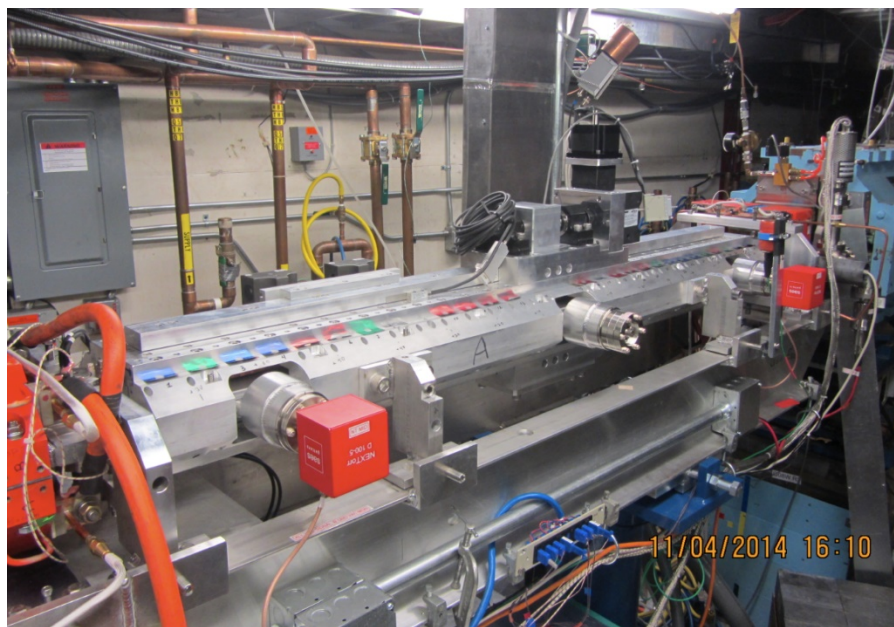


New system

- IGUS PTR bearing
- Axial and radial bearing
- Non magnetic
- No maintenance
- Long term continuous use
- New stable software

Cornell Compact Undulator

- ◆ Closed structure undulator
- ◆ Fixed gap device (~ 7 mm gap)
- ◆ Field tuning achieved by longitudinal phasing of magnets
- ◆ Vacuum compatible



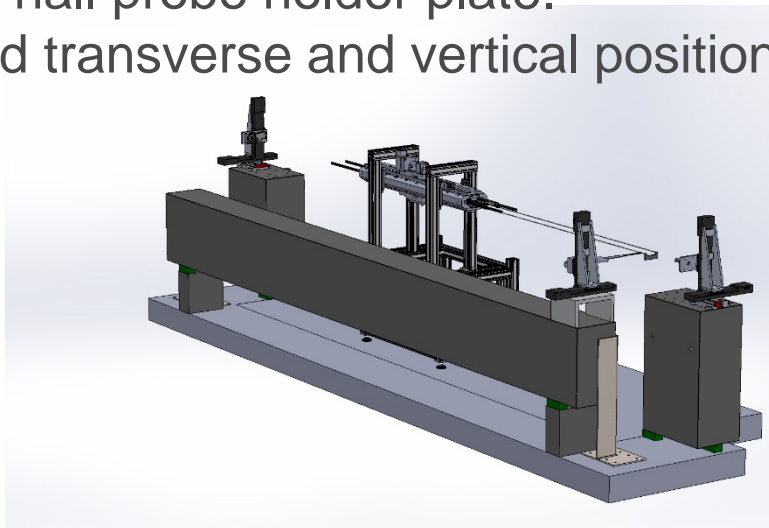
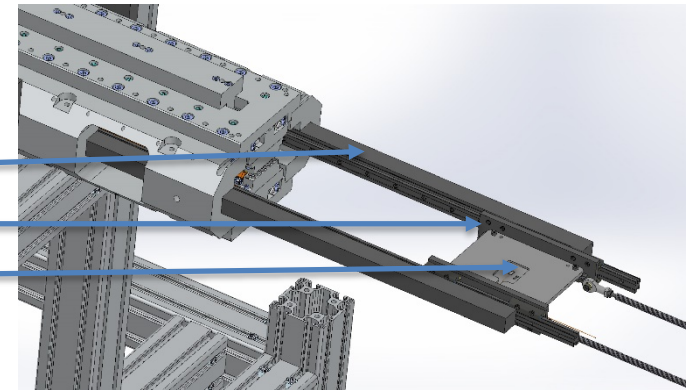
CCU measurement bench

Requirements

- Measurement of closed structure
- Reuse of the driving mechanism of old measurement bench
- Mechanical position accuracy of 50 μm

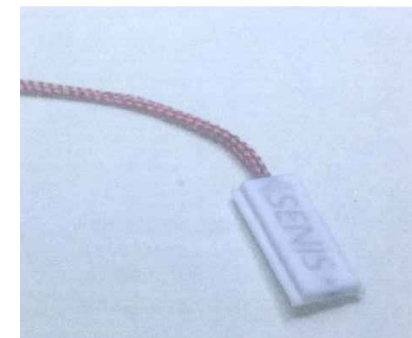
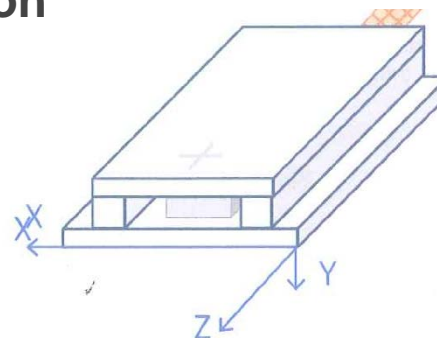
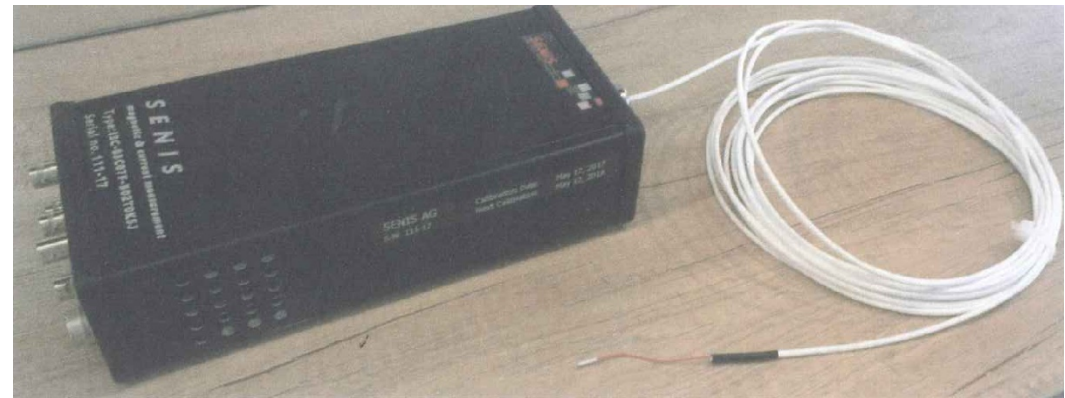
Solutions

- Aluminum precision machined bars
- IGUS guide rails
- FR4 hall probe holder plate.
- Fixed transverse and vertical position



Senis type C probe with I3C transducer

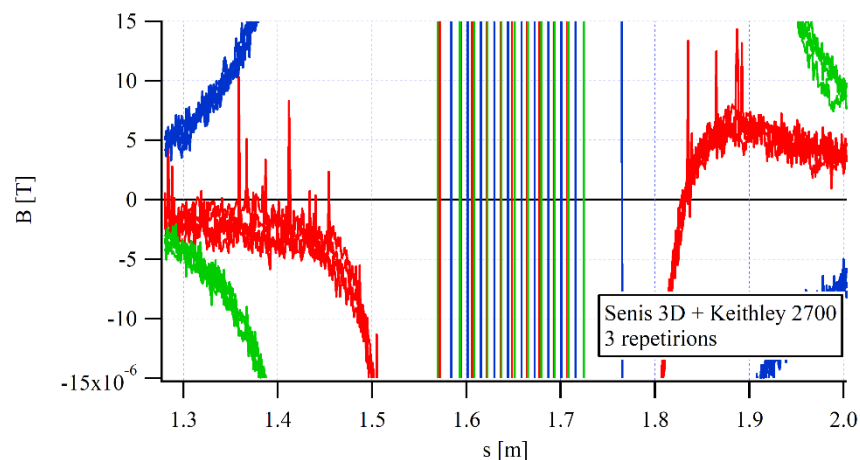
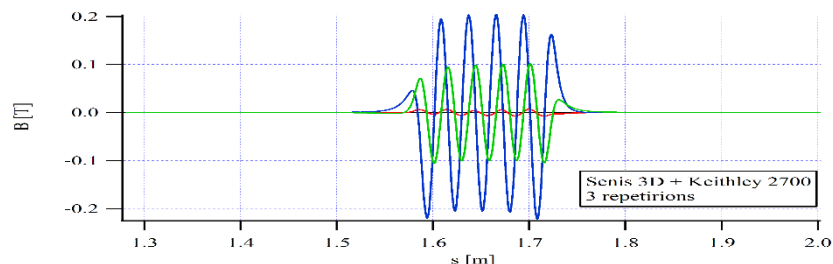
- ◆ I3C-0307F-B02T0K5J
- ◆ 3D probe for point measurements
- ◆ Small profile probe
- ◆ Small detector:
 - ◆ $Y: 30 \times 5 \times 30 \text{ } \mu\text{m}^3$
 - ◆ $X, Z: 100 \times 10 \times 100 \text{ } \mu\text{m}^3$
- ◆ Very good linearity
- ◆ Low noise and drift
- ◆ Can be used on measurement system without any modification (hardware or software)



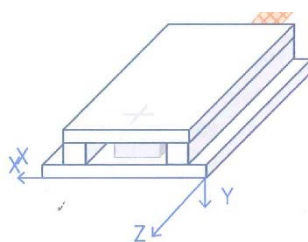


Senis probe – first measurements 1/2

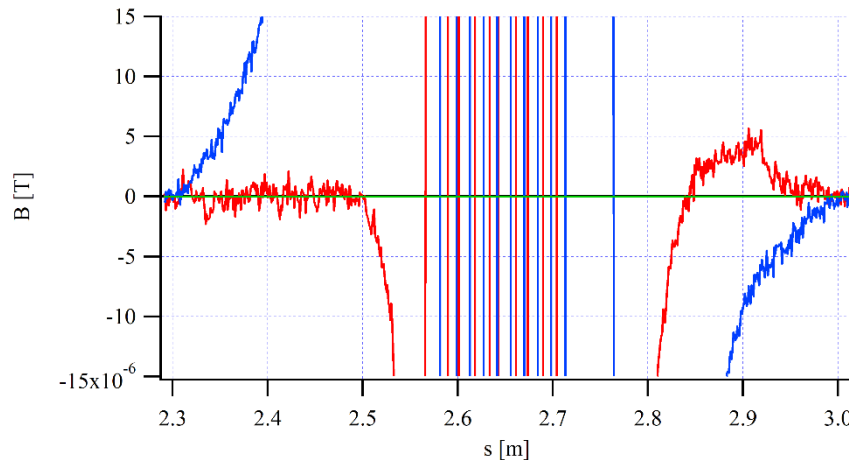
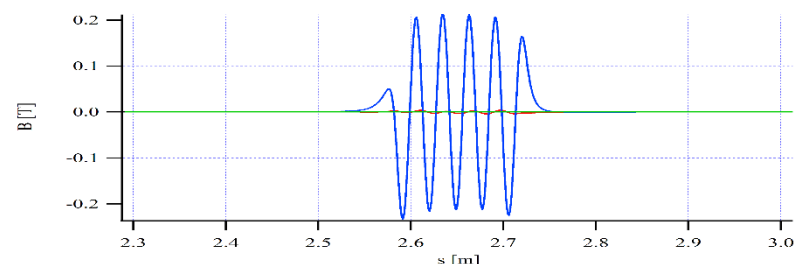
Senis Type C probe



	Std. Dev. [μT]
Bx – Z	1.45
Bz – Y	0.66
Bs – X	0.66



Senis Type I probe



	Std. Dev. [μT]
Bx – Z	0.81
Bz – Y	4.22
Bs – X	NA

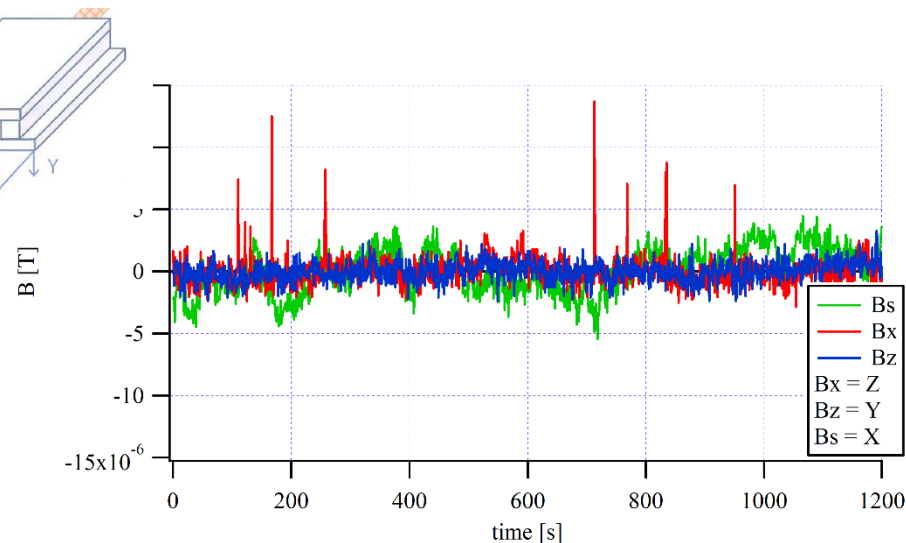
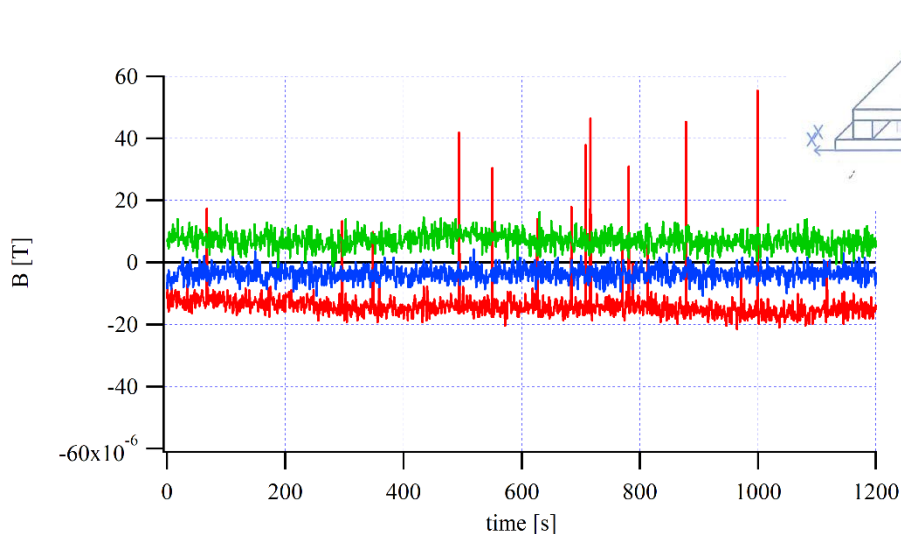


Senis probe – first measurements 2/2

Long term stability and drift for 20 minutes

	Average [μT]	Std. Dev. [μT]
Bx – Z	-14	5.3
Bz – Y	-3.6	2.3
Bs – X	7.1	2.6

	Average [mT]	Std. Dev. [μT]
Bx – Z	3.7	6.2
Bz – Y	0.1	4.3
Bs – X	-2.1	9.0



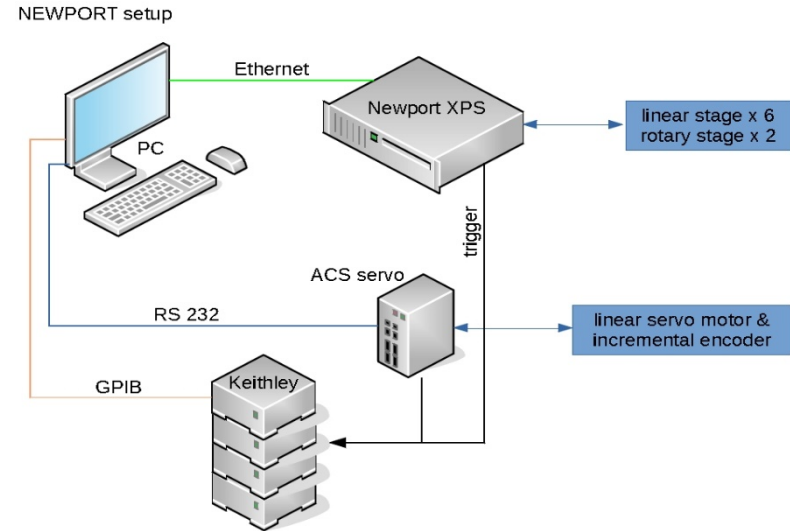
Keithley 2700 DMM – shorted inputs

Keithley 2700 DMM + Senis type C probe. Average subtracted

Universal measurement bench CS

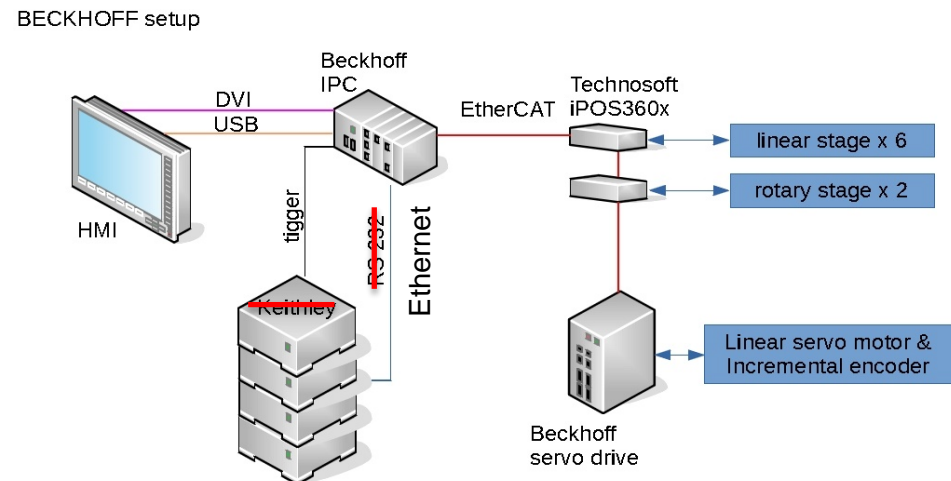
Old ESRF System

- ◆ *Newport XPS controller – works only with old version C8*
- ◆ *ESRF bench control software – no source code*
- ◆ *Igor Pro 6.12 and below*



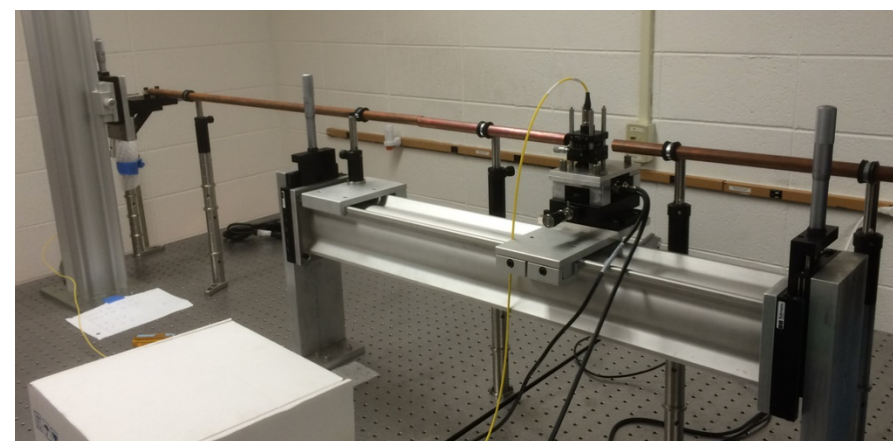
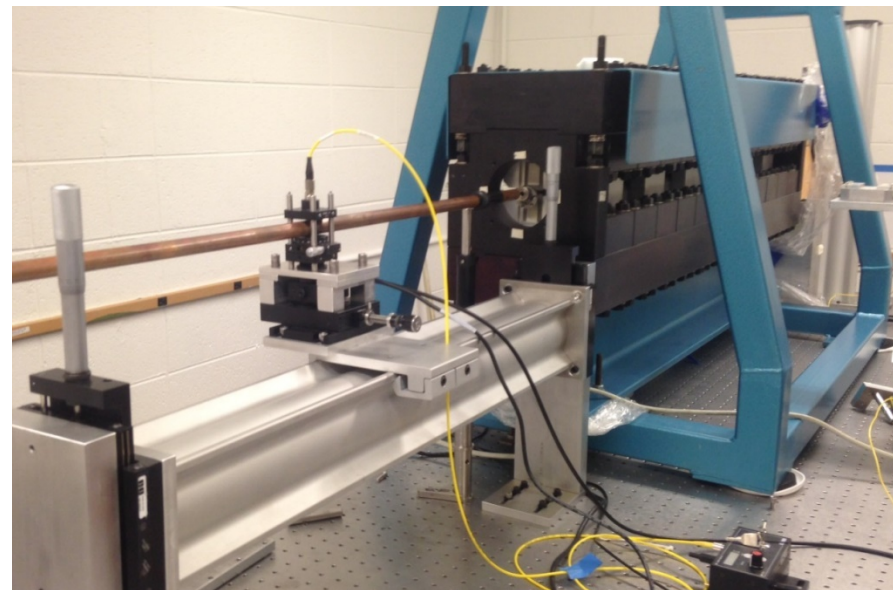
New Kyma Control System

- ◆ *Flexible Beckhoff motion control*
- ◆ *Possibility to use any motion and measurement hardware*
- ◆ *Python interface*



Pulsed wire from CSU

- ◆ *Acquired from Colorado State University*
- ◆ *High resolution measurements of small and closed gap devices.*
- ◆ *Measurement and processing software provided by CSU. Including dispersion correction algorithm.*
- ◆ **Current status**
 - ✧ Design of mechanical supports
 - ✧ Expected commissioning in fall 2017





Thank you!

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